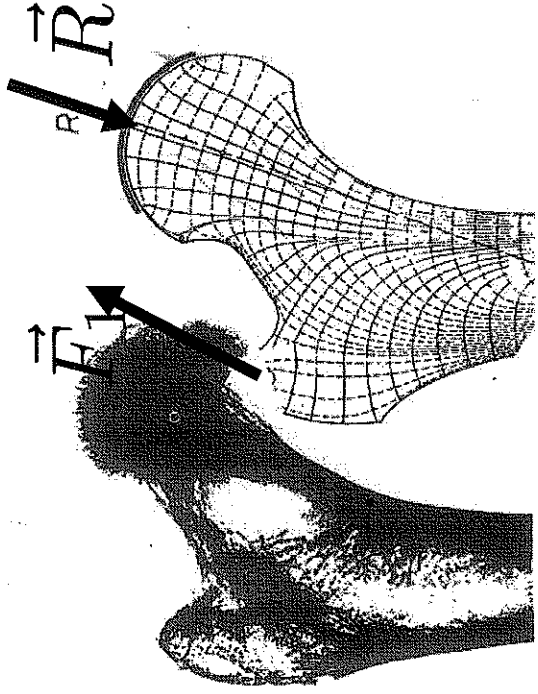
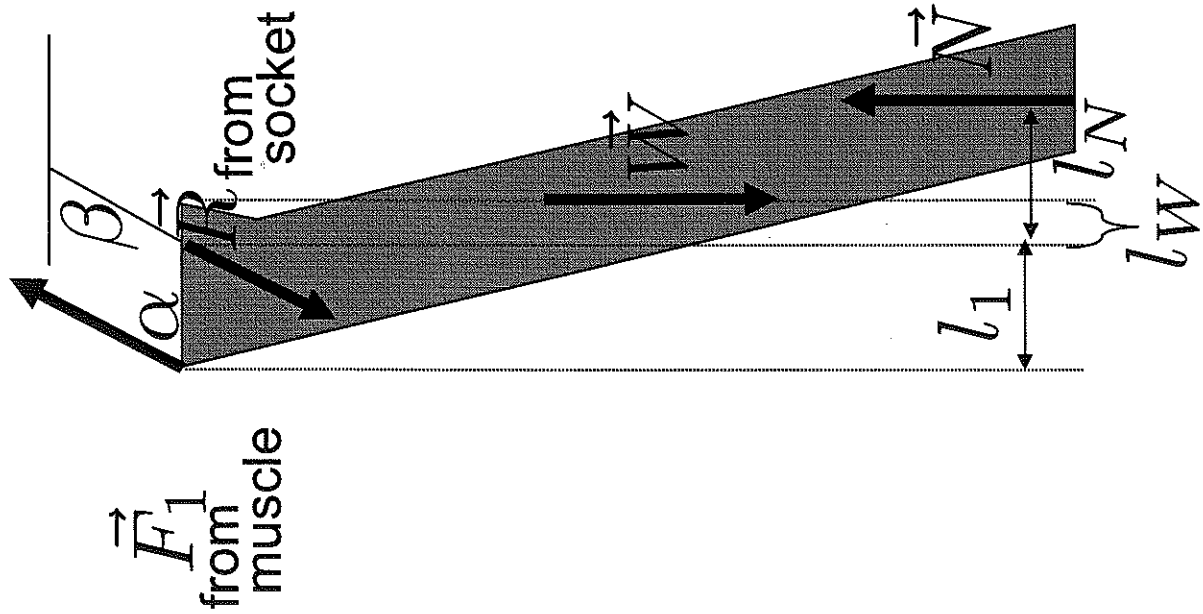


Example: human hip



From Benedek and Villars,
*Physics with Illustrative Examples from
 Medicine and Biology: Mechanics*

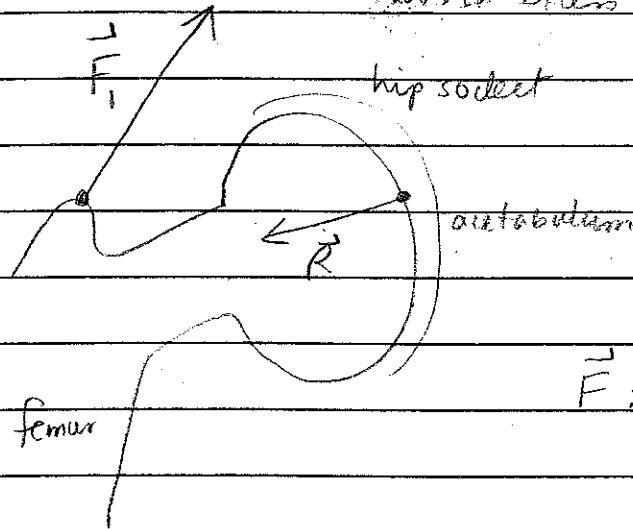
**If you are balancing on
 one leg, what is the force on
 your hip from the socket?**

Known: $\alpha=70^\circ$, m , l_W , l_N , l_1 , $W=mg/7$

Unknown: β , R , F_1

Human Hip

medical application
 orthopaedic experts, physical therapists,
 biomed engineers, learn how to support
 the body \rightarrow which muscles to strengthen,
 how to avoid pain, promote healing,
 avoid ^{excess} bone growth, etc



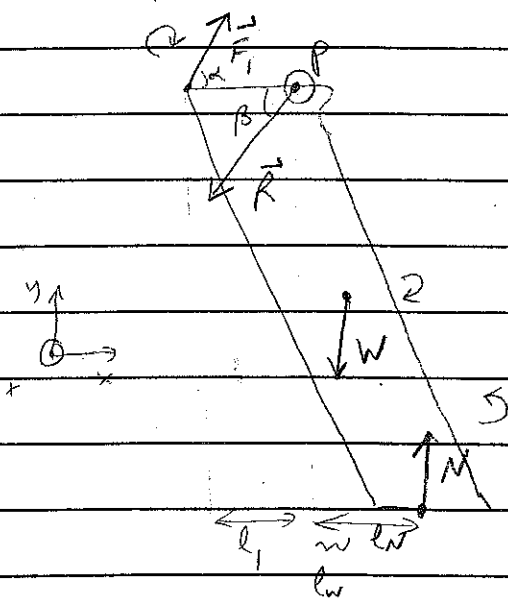
\vec{R} : force of acetabulum
 on femur, \perp to
 curved surface

\vec{F} : force from hip abductor
 muscle

Balancing on one leg (e.g. momentarily while walking)
 \rightarrow what is R

Simplified version of leg FBD

- 1) diagram
- 2) pivot
- 3) \pm dir
- 4) sense of rotation



Known: $d = 70^\circ$

$m, l_1, l_w, l_N, N = mg$

$W = mg/7$ since
 supporting whole
 body

These are all
 things one could measure
 for a person

Unknown β, R, F_1

5) Force balance on leg $\sum F_x = 0$

$$\textcircled{1} F_1 \cos d - R \cos \beta = 0$$

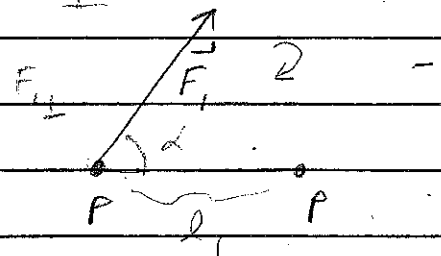
$$\Sigma F_y = 0$$

$$F_1 \sin \alpha + N - m_L g - R \sin \beta = 0 \quad (2)$$

6) Torque balance $\Sigma \vec{\tau} = 0$

$$\tau_p \text{ due to } \vec{R} = 0$$

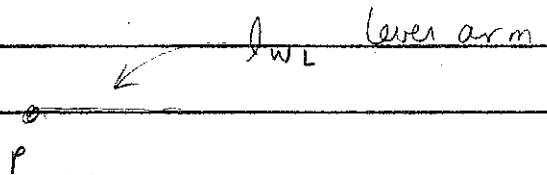
$$\tau_p \text{ due to } \vec{F}_1$$



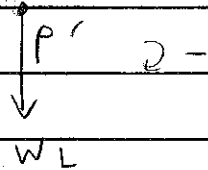
Use \perp force method

$$\tau_{pF_1} = -F_1 l_1 \sin \alpha$$

$$\tau_p \text{ due to } W_L$$

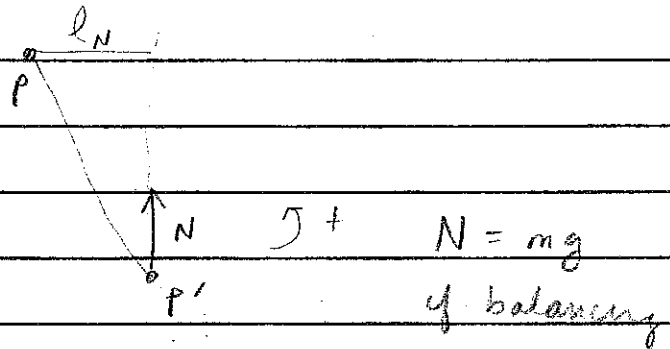


$$\tau_{pWL} = -l_{WL} W_L$$



$$\tau_p \text{ due to } N$$

$$\tau_{pN} = +l_N N$$



$$\text{Sum } \Sigma \tau = \tau_{pF_1} + \tau_{pW} + \tau_{pN} = 0$$

$$\alpha = 70^\circ$$

$$l_1 = 2.75''$$

$$l_W = 1.25''$$

$$l_N = 4.25''$$

$$0 = -l_1 F_1 \sin \alpha - l_W m_L g + l_N N$$

$$(3) F_1 = \frac{l_N m g - l_W m_L g}{l_1 \sin \alpha} = \underline{\underline{1.6 m g}}$$

quite a force!
more than
your weight

3 eqns, 3 uk

$$\textcircled{2} \Rightarrow R \sin \beta = F_1 \sin \alpha - m_L g + m g$$

$$\textcircled{1} \Rightarrow R \cos \beta = F_1 \cos \alpha$$

Divide $\tan \beta = \frac{m g - m_L g}{F_1 \cos \alpha} = 4.3$

$$\Rightarrow \beta = 77^\circ$$

$$|\vec{R}| = F_1 \frac{\cos \alpha}{\cos \beta} = 2.4 m g !$$

2.4 times your weight
in your hip socket when
you balance on one leg!

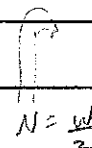
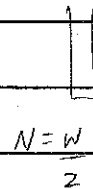
Hip injuries can be very painful

↳ orthopaedist can
use this knowledge

$$F_1 = \frac{l_N m g - l_W m_L g}{l_1 \sin \alpha}$$

→ Reduce l_N to reduce F → put foot
directly under hip

Or, we can
to support
weight



$$l_N m g \rightarrow \frac{l_W m g}{2}$$