

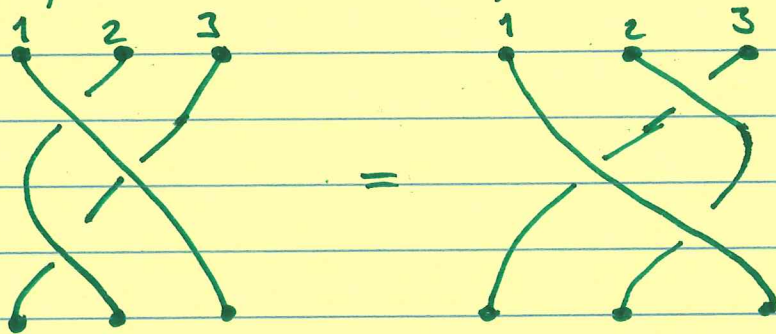
References: Kauffman Knot & Physics  
Introduction to representations of braid groups

I. Yang Baxter equation: - Camilo Arias Abad  
minicourse at Cimpa

consistency equation introduced first in statistical mechanics (e.g. 2D Ising Model)

"in some scattering situation, particles may preserve their momentum while changing quantum internal states"

"the interaction between 3 particles is determined by the two particle interactions & is independent of which particles interact first."



$$R^{12} R^{13} R^{23} = R^{23} R^{13} R^{12} \quad \text{YB eqn.}$$

$R^{ij}$  is an endomorphism of  $\mathbb{C}^n \otimes \mathbb{C}^n \otimes \mathbb{C}^n$  on the two factors  $i, j$  & leaving the third factor alone.

Key cool fact: Solutions of the YB eqn produce representations of the braid group.

~~These~~ Representations of the braid group are also related to knot invariants!

Goal: Sketch how a soln to YB eqn gives us the Jones polynomial. An important knot inv.

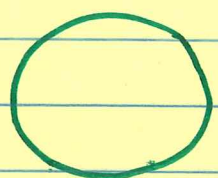
# I. Background: KNOTS + Braids.

Defn A knot is an embedding  $S^1 \hookrightarrow \mathbb{R}^3$   
or  $(S^1 \hookrightarrow S^3 = \mathbb{R}^3 \cup \{\infty\})$ .

$n$ -component

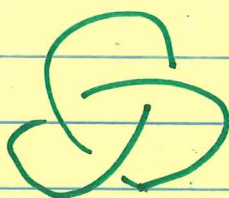
An link is an embedding of  $n$  disjoint circles into  $\mathbb{R}^3$

Projections of knots to  $\mathbb{R}^2$

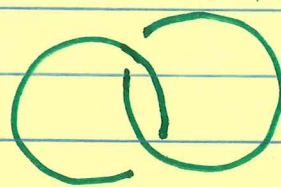


unknot

$\neq$



trefoil



Hopf link

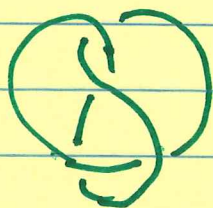


fig 8 knot.

We say two ~~knots~~ <sup>links</sup>  $K_1, K_2$  are ambient isotopic  
if  $\exists$  an ambient isotopy btwn them

This is a ~~map~~ conts map

$$\phi_t : \mathbb{R}^3 \times I_t \longrightarrow \mathbb{R}^3$$

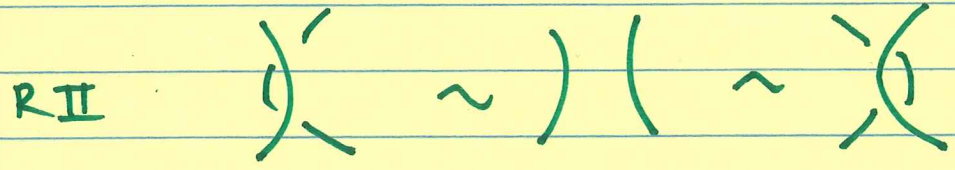
s.t.  $\phi_0 = \text{Id}$

$\phi_t : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$  homeomorphism

$\phi_1(K_1) = K_2$ .

[Reidemeister] THM Two diagrams of links represent isotopic links if one can be transformed into the other by a finite sequence of 3 types of moves called Reidemeister moves


Fundamental group  $\pi_1(X \setminus x_0)$  loops in space  $X$  based at  $x_0$  / homotopy



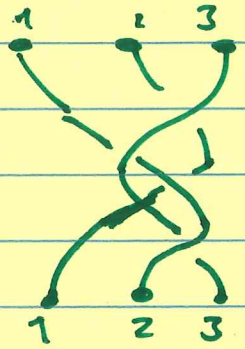
The question of how to distinguish non-isotopic knots was attacked with knot invariants (e.g. minimal crossing number, Seifert genus,  $\pi_1(\mathbb{R}^3 \setminus K)$ , polynomials, ...)

Thanks to Reidemeister's thm, if you want to construct a knot inv from diagrams/projections of knots you just need to check that it doesn't change under Reidemeister moves.

homotopy: continuously deform one config. map to another.

Braids: 

Defn: Take  $n$ -pts on the plane,  $n$ -paths



$$f_i: I \rightarrow D^2$$

$$f_i(0) = p_i \quad f_i(1) = p_{\tau(i)}$$

$$f_i(t) \neq f_j(t) \quad (i \neq j)$$

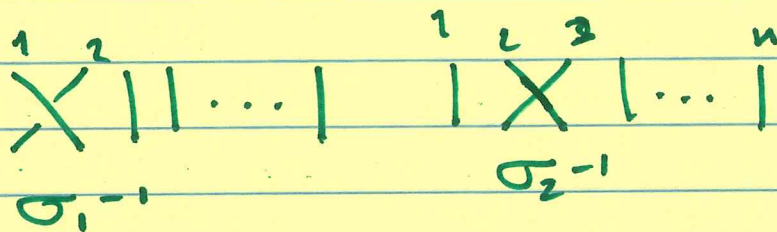
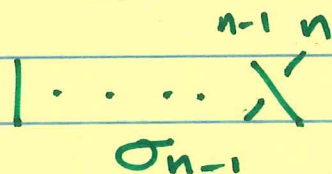
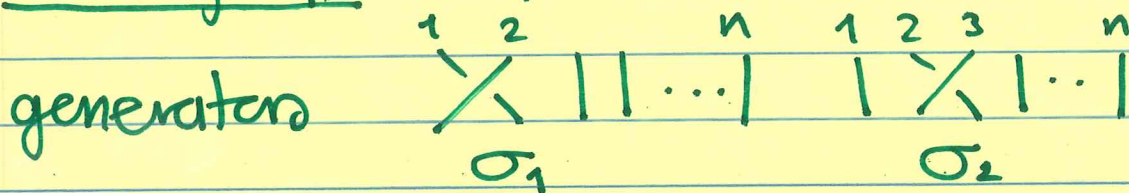
↑ permutation in  $S_n$

Note: Mapping Class group of the disk with  $n$  punctures (orientation preserving homeomorphisms of  $D^2$  that fix punctures as a set)

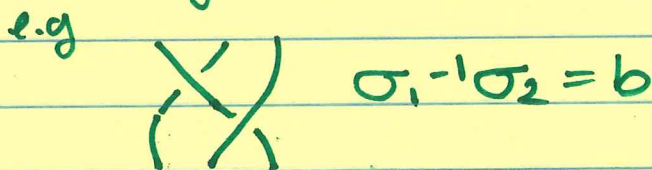
Can think of braids as diagram of a physical process of particles interacting or moving about in the plane. where time is moving up vertically



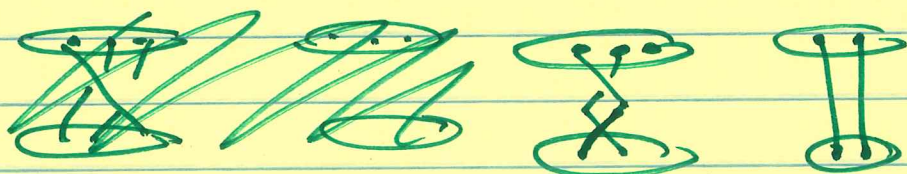
Braid group  $B_n$  (n pts)



Then any braid  $b \in B_n$  is a word

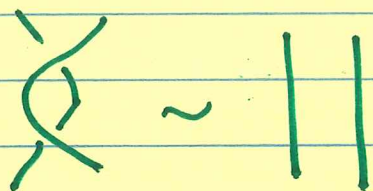


Q when are two braids  $b, b' \in B_n$  equivalent  
 If there exists an ambient isotopy from  $b$  to  $b'$  that keeps endpoints fixed & strands don't move outside top + bottom planes of braids.

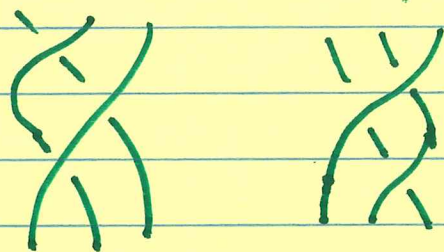


$$i = 1, \dots, n-1$$

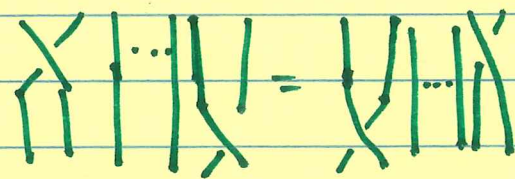
$$B_n = \langle \sigma_i, \sigma_i^{-1} \mid \begin{array}{l} \sigma_i \sigma_i^{-1} = 1 \quad i=1, \dots, n-1 \\ \sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1} \quad i=1, \dots, n-2 \\ \sigma_i \sigma_j = \sigma_j \sigma_i \quad |i-j| > 1 \end{array} \rangle$$



$$\sim \parallel \parallel \quad \sigma_i \sigma_i^{-1} = 1$$



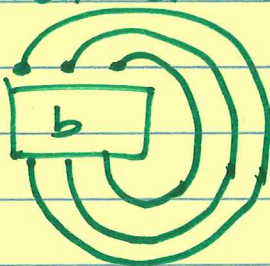
$$\sigma_1 \sigma_2 \sigma_1 = \sigma_2 \sigma_1 \sigma_2$$



$$\sigma_i \sigma_j = \sigma_j \sigma_i \quad |i-j| > 1$$

Q: How are braids related to knots?

[Alexander] Given a braid  $b \in B_n$  its closure  $\bar{b}$  is:



Any knot or link can be put in the form of a closed braid (via ambient isotopy)

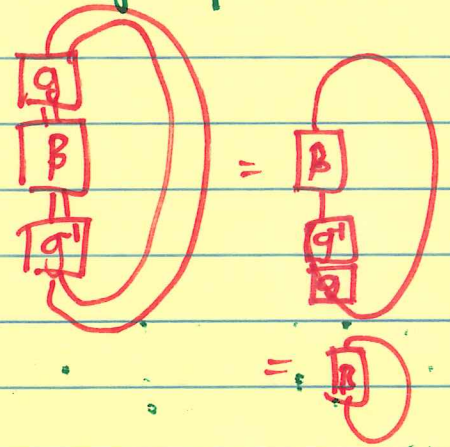
Q How many different ways can a link be represented as a closed braid?

[MARKOV]  $\beta_n \in B_n$ ,  $\tilde{\beta}_m \in B_m$  two braids

$\beta_n \sim \tilde{\beta}_m$  as links iff  $\tilde{\beta}_m$  can be obtained from  $\beta_n$  via

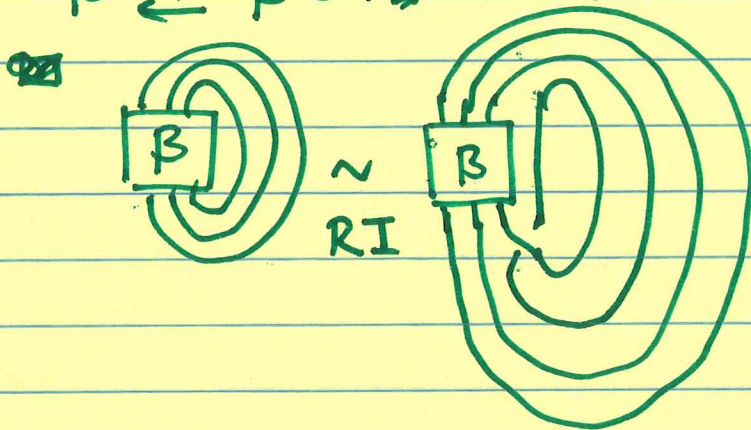
- (1) Equivalences in a given braid group
- (2) conjugation

$$g\beta g^{-1} \sim \beta$$



- (3) Markov moves

$$\beta \Leftrightarrow \beta \sigma_n^{\pm 1} \in B_{n+1}$$



[Now: We can use presentations of braid group  $B_n$  to extract topological info about knob + links.

Markov trace on  $B_n$

$$J_n: B_n \rightarrow \boxed{R} \text{ ring } R$$

we need  $J_n(\beta) = J_n(g\beta g^{-1}) \quad J_n(\beta) = J_n(\tilde{\beta})$

$$J_n(\beta \sigma_n) = \alpha^{+1} J_n(\beta)$$

↑ same const.

$$J_{n+1}(\beta \sigma_n^{-1}) = \alpha^{-1} J_n(\beta)$$

Then if  $w(b) = \sum_{i=1}^k a_i$  for  $b = \sigma_{i_1}^{a_1} \sigma_{i_2}^{a_2} \dots \sigma_{i_k}^{a_k}$

$J(L) = \alpha^{-w(b)} J_n(b)$  is a link invariant

for  $(L = \bar{b})$  for  $\{J_n\}$ .

|| JONES POLYNOMIAL + BRACKET POLYNOMIAL. ||

More generally:  $V$  complex vector space,  
 an automorphism  $R$  of  $V \otimes V$  is an  $r$ -matrix  
 if it satisfies the YB

$$(R \otimes \text{id}) \circ (\text{id} \otimes R) \circ (R \otimes \text{id}) = (\text{id} \otimes R) \circ (R \otimes \text{id}) \circ (\text{id} \otimes R) \in \text{End}(V^{\otimes 3}).$$

LEMMA: Given a  $r$ -matrix  $R \in \text{Aut}(V \otimes V)$   
 $\exists$  representation

$$\rho_R : B_n \rightarrow \text{Aut}(V^{\otimes n})$$

$$\sigma_i \mapsto \text{id}^{i-1} \otimes R \otimes \text{id}^{n-i-1}$$

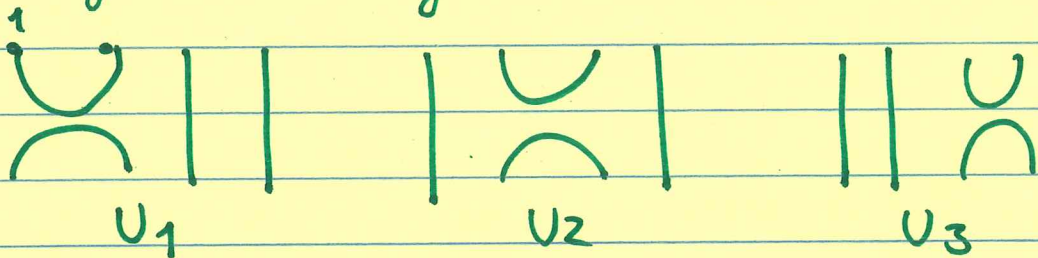
PR

$\rho(\sigma_i \sigma_j) = \rho(\sigma_j \sigma_i)$   $|i-j|$  clearly works

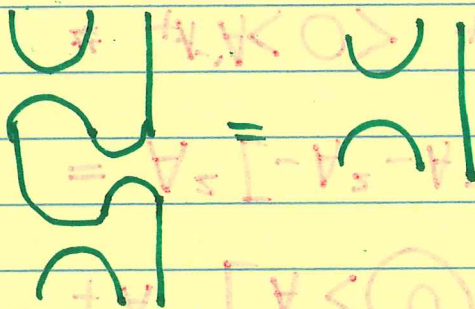
$$\rho(\sigma_i) \rho(\sigma_{i+1}) \rho(\sigma_i) = \rho(\sigma_{i+1}) \rho(\sigma_i) \rho(\sigma_{i+1}) \text{ by YB}$$

Jones + bracket polynomial:

Consider the following Temperley-Lieb algebra ~~that~~ generated by  $U_i$



Then  $U_i U_{i+1} U_i = U_i$



$U_i^2 = \delta U_i$



$U_i U_j = U_j U_i \quad |i-j| > 1$

Consider the following mapping

$\rho(\sigma_i) = A + A^{-1} U_i$

$\langle \dots \times \dots \rangle = A \langle \dots \mid \text{Id} \rangle + A^{-1} \langle \dots \times \dots \rangle$



$$\rho(\sigma_i^{-1}) = A^{-1} + AU_i$$

~~$$\rho(B) = \text{tr} \left[ \rho(A, A^{-1}) \right]$$~~

~~by setting any loop  $\langle \bigcirc \rangle = S$   $\langle \bigcirc \rangle = S$~~

~~$\langle \bigcirc \rangle = \langle \bigcirc \rangle$  is called the bracket polynomial~~

Now consider  $\text{tr}: A_n \rightarrow \mathbb{Z}[A, A^{-1}]$  where  
 $\text{tr}(U) = \langle U \rangle = \delta^{\|U\|}$   
 ↑  
 the number of closed loops

$\Rightarrow \langle \bigcirc \rangle = \text{tr}(\rho(\bigcirc))$  & we have defined the bracket polynomial.

Note that

$$\langle \bigcirc \rangle = \sum_s \langle \bigcirc | s \rangle \langle \bar{U}_s \rangle$$

state weights  $A, A^{-1}$

$\sum_s \delta^{\|U_s\|-1}$

~~$$\langle \bigcirc \rangle = A \langle \bigcirc \rangle + A^{-1} \langle \bigcirc \rangle$$~~

~~$$FCAR \text{ R R 2 4}$$~~

for  $\langle \bigcirc \rangle = \langle \bigcirc \rangle \text{ R II}$

$$\Rightarrow S = (-A^2 - A^{-2})$$

~~$$\langle \bigcirc \rangle = \langle \bigcirc \rangle \text{ R III} \quad (A + A^{-1})(A^{-2} - A^2)$$~~

But  $\langle \bigcirc \rangle = A \langle \bigcirc \rangle + A^{-1} \langle \bigcirc \rangle$

~~$$\langle \bigcirc \rangle = A \langle \bigcirc \rangle + A^{-1} \langle \bigcirc \rangle$$~~

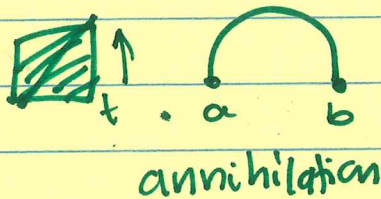
So we add a normalizing factor  $(-A^3)^{-w(\beta)}$

$w(\beta) = w(\text{the of a braid})$ .

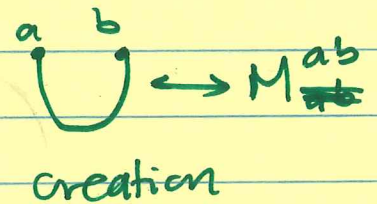
Then if we let  $A = t^{-1/4}$  we get the Jones polynomial, which is a knot invariant

Jones is a specialization of the trace of a rop of  $B_n$ .

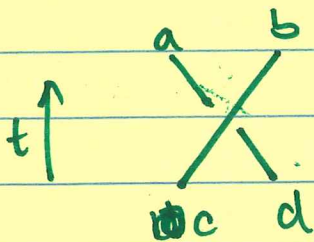
Toy Physics example:



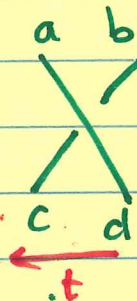
$$\leftrightarrow M_{ab}$$



$$\leftrightarrow M_{\overline{ab}}$$

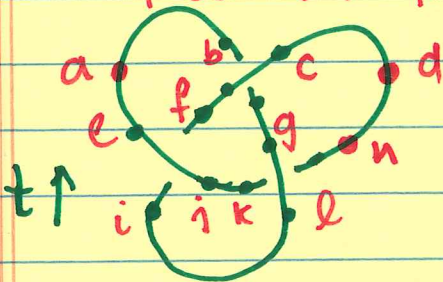


$$\leftrightarrow R_{cd}^{ab}$$



$$\leftrightarrow \overline{R}_{cd}^{ab}$$

they are differentiated by time  $t$  could be diff interactions or  
if we ask for  $\overline{R}_{cd}^{ab} = R_{db}^{ca}$



$$T(K) = M\text{'s} \ \& \ R\text{'s}$$

$$= M_{ab} M_{cd} R_{bc} \dots$$

$$= M_{ab} M_{cd} \delta_e^a \delta_h^g R_{fg}^{bc} \overline{R}_{ij}^{ef} \overline{R}_{kl}^{gh} M_{il} M_{jk}$$

$T(K)$  vacuum to vacuum expectation.

In a highly simplified QFT of link diagrams.  
We want  $T(K)$  to be a topological inv of reg isotopy (moves II+III)